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A visco-elastic model for liquefaction of sands

Un modèle visco-élastique de la liquéfaction des sables

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SYNOPSIS An equivalent visco-elastic model consisting of 4 formulas for calculating the shear modulus, the damping ratio and the volumetric and deviatoric strains of sands during cyclic loading is proposed. The model, together with the effective stress method for dynamic response analysis, can be used to solve practical problems associated with seismic stability of sand masses.

INTRODUCTION

The author proposed an equivalent visco-elastic model several years ago (Shen & Wang, 1980), but it turned out to be a little complicated for practical use. In the following this model is revised and simplified, and a laboratory procedure is suggested to determine the related soil constants.

PROPOSED MODEL

Theoretically, the deformation characteristics of sands under cyclic loading as well as under static condition are better simulated by using elasto-plastic models. But the research of this kind has just begun, and the theories suggested by various authors seem far from being able to solve practical problems. A visco-elastic model aims to simulate the soil stress-strain behaviour in a cycle of loading as a whole but not in detail (Fig.1). It is said that the model gives equivalent hysteresis loops if the axis of inclination and the enclosed area of stress-strain ellipse are essentially equal to those of the actual stress-strain loops. A hysteresis loop can be characterized by the shear modulus G and damping ratio D , and the plastic deformation can be divided into the volumetric and deviatoric components $\Delta \epsilon^p$ and $\Delta \gamma^p$. Therefore, a complete set of relationships for the visco-elastic model must include 4 formulas.

For a given sand there are three fundamental factors affecting its deformation characteristics in a particular loading cycle, i.e. the initial static stress (σ_s, τ_s), the amplitude of cyclic stress τ_d or strain γ_d and the loading history

characterized by the accumulated shear straining $\xi = \sum_{i=1}^{r-1} (\gamma_d)_i$, where $\sigma_s = \frac{1}{2}(\sigma_1 + \sigma_3)$, $\tau_s = \frac{1}{2}(\sigma_1 - \sigma_3)$, $\gamma = \epsilon_1 - \epsilon_3$, σ_1, σ_3 - principal stresses (in term of effective stress), ϵ_1, ϵ_3 - principal strains, and r is the number of current cycle, with $(\gamma_d)_i$ shear strain amplitude of i th cycle of loading. The subscripts s and d refer to the static and dynamic states respectively. Taking these factors into account and using γ_d as an independent variable the proposed formulas are as follows

$$G = \frac{k_s}{1 + k_d \gamma_c} (\sigma_s)^{\frac{1}{2}} \tag{1}$$

$$D = D_{max} \frac{k_d \gamma_c}{1 + k_d \gamma_c} \tag{2}$$

$$\Delta \epsilon^p = c_d (\gamma_d)^{c_2} \exp(-c_3 R_s^2) \frac{1}{1 + N_e} \tag{3}$$

$$\Delta \gamma^p = c_d (\gamma_d)^{c_3} R_s^2 \frac{1}{1 + N_e} \tag{4}$$

where

$$\gamma_c = (\gamma_d)^{\frac{1}{2}} (\sigma_s)^{-\frac{1}{2}} \tag{5}$$

is the corrected shear strain amplitude,

$$N_e = \frac{\xi}{\gamma_d} \tag{6}$$

is the effective number of loading cycles, and

$$R_s = \frac{\tau_s}{\sigma_s \sin \phi} \tag{7}$$

is the shear stress level, ϕ - angle of internal friction. Under undrained condition the pore pressure increment can be calculated by

$$\Delta u^p = K_u \Delta \epsilon^p \tag{8}$$

where K_u is the unloading bulk modulus

$$K_u = k_u (\sigma_s)^{\frac{1}{2}} \tag{9}$$

In the abovementioned formulas $c, c_2, c_3, c_d, c_s, k, k_d, k_u, D_{max}$ and ϕ are soil constants.

DISCUSSION AND COMPARISON

Relationship (1) is essentially the same as that suggested by Hardin & Drnevich (1972). If it is assumed that the so-called hyperbolic strain γ_d

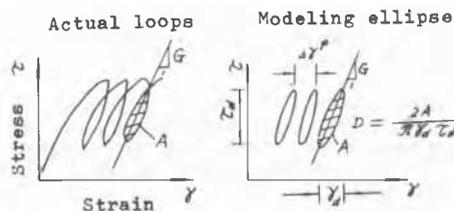


Fig.1. Visco-Elastic Model

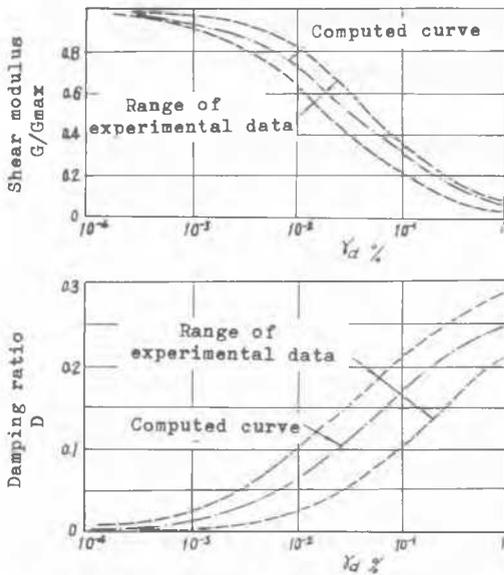


Fig.2 Shear Modulus and Damping

is simply equal to γ_d , then their formula can be written as follows

$$G = \frac{k(G_s)^{\frac{1}{2}}}{1 + k/\sin\phi \gamma_d (G_s)^{-\frac{1}{2}}} \quad (10)$$

where $k = 325 \frac{(2.973 - e)^2}{1 + e}$, e - void ratio and G_s in kg/cm^2 . Comparison of formulas (1) and (10) yields $k_1 = k/\sin\phi$, $k_2 = k$ and $(\gamma_d)^{\frac{1}{2}}$ instead of γ_d in Eq.(10). The last revision aims to make the calculated results better fitted to experimental data. The proposed formula (2) for damping ratio is also similar with that of Hardin and Drnevich. The curves of shear modulus and damping versus shear strain amplitude calculated from Eq.(1) and (2) for $G_s = 1 kg/cm^2$, $k = 10$ and $D_{max} = 0.27$ are compared with the experimental data (Seed & Idriss, 1970) in Fig.2, where $G_{max} = k_1 (G_s)^{\frac{1}{2}}$. When G_s increases formula (1) will give a little higher values of shear modulus than those in Fig.2.

When a fresh sample is loaded, $N_e = 0$ and formulas (3) and (4) can be written as

$$(\Delta \epsilon^l)_1 = c_1 (\gamma_d)^{c_2} \exp(-c_3 R_s) \quad (11)$$

$$(\Delta \gamma^l)_1 = c_4 (\gamma_d)^{c_5} R_s^2 \quad (12)$$

where subscript 1 means the first loading cycle. For isotropically consolidated samples, $R_s = 0$, and these formulas become

$$(\Delta \epsilon^l)_1 = c_1 (\gamma_d)^{c_2}, \quad (\Delta \gamma^l)_1 = 0$$

In the abovementioned formulas the amplitude of shear strain is adopted as a main variable, as firstly suggested by Martin et al.(1975). Yokel et al.(1980) further argued about the advantage of shear strain approach over shear stress approach. However, the threshold strain is neglected and a simple power function is assumed for the relationships between $\Delta \epsilon^l$ and γ_d as well as $\Delta \gamma^l$ and γ_d .

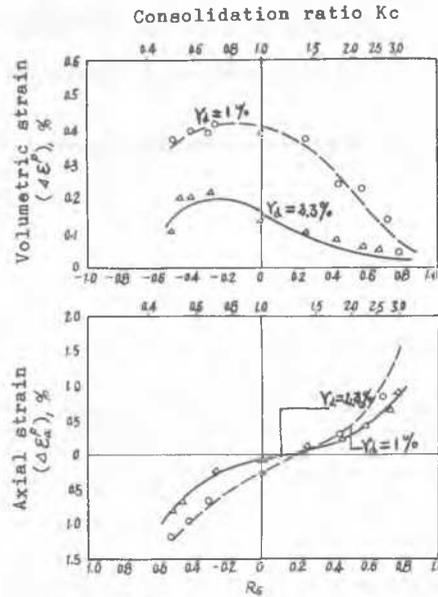


Fig.3 Residual Deformation

The multipliers with R_s in Eq.(11) and (12) account for static stress state before applying current cycle of loading. The assumption of error function and parabolic law of change of $(\Delta \epsilon^l)$ and $(\Delta \gamma^l)$ versus R_s is supported by the experimental data of a medium sand (Shen & Wang, 1980) as shown in Fig.3, where the negative R_s means that the lateral confined stress $(\sigma_r)_c$ is larger than the axial stress $(\sigma_a)_c$. The unsymmetrical shape of curves are probably due to the inherent anisotropy of samples introduced during their preparation, which results in more compressibility of samples in the radial direction than in the axial direction.

The multiplier $\frac{1}{1+N_e}$ in Eq.(3) and (4) accounts for decreasing rate of build-up of residual deformation with the increase of loading cycles. More complicated multipliers have been proposed by Ishibashi (1977) and others. Fig.4 shows the experimental data of rate of pore pressure generation and uniform strain amplitude of various levels. Naturally, in this situation N_e is equal to actual cycle number N . It seems that the approximation of this simplest function is acceptable, although the more complicated one fits the experimental results a little better.

DETERMINATION OF SOIL CONSTANTS

A detailed description of the proposed procedure to determine the soil constants in related formulas has been given (Shen, 1984). Its main points are outlined below.

i). The modulus numbers k_1 and k_2 can be determined by cyclic triaxial test accompanied with resonant column test. When the test data are not available it is recommended to use Rechart's formula (1977)

$$k_1 = 700 \frac{(2.17 - e)^2}{1 + e} \quad (13)$$

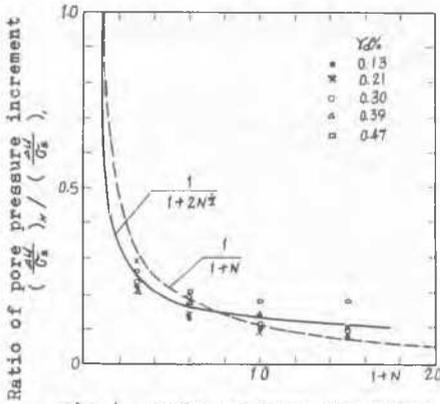


Fig.4 Rate of Pore Pressure Generation

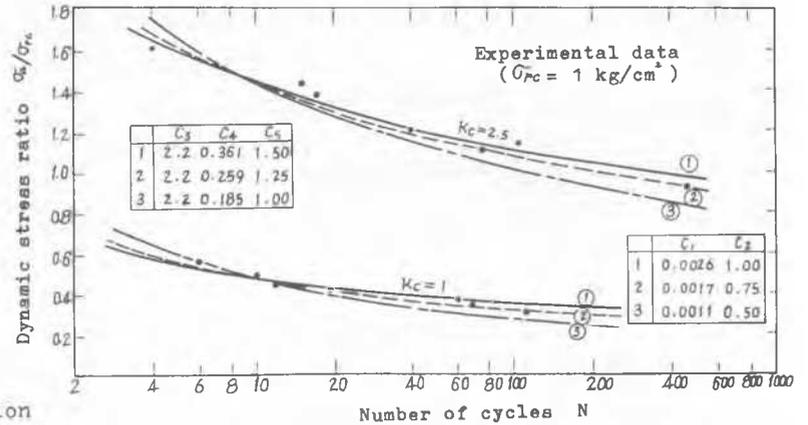


Fig.5 Cyclic Strength of Chaihe Sand

and to take $k_v=10$ or $k_v=6$ when double amplitude γ_0 is used in Eq.(5). D_{max} is assumed equal to 0.27 in case of sands.

ii). The residual deformation coefficients c_1 , c_2 , and c_3 can be determined from cyclic triaxial test data under certain prescribed values c_2 and c_3 . Meanwhile, c_1 is obtained by testing isotropically consolidated samples, and c_2 and c_3 - samples consolidated under stress ratio $K_c=2$ or 2.5. A computer program SCUDA has been developed to determine these coefficients. Fig.5 shows the cyclic strength curves of Chaihe sand (a medium sand with relative density 60%) computed with 3 different values of c_1 and c_2 for isotropically and anisotropically consolidated samples respectively. The failure criterion for the

anisotropically consolidated samples is 5% residual axial strain. The experimental results are also shown in the Figure. It seems that the influence of c_1 and c_2 on the form of curves is not very large, and it is recommended to take $c_2 = 3/4$ and $c_3 = 1$ for most of sands.

iii). An all-round static compression and rebound test is needed to determine the unloading modulus number k_u . Attention must be paid to correct the membrane penetration effect in such a test. The loading modulus number k_l can also be deduced from this test. The another shear modulus number k_s used in static stress analysis as well as angle of internal friction ϕ can be determined from static triaxial test results.

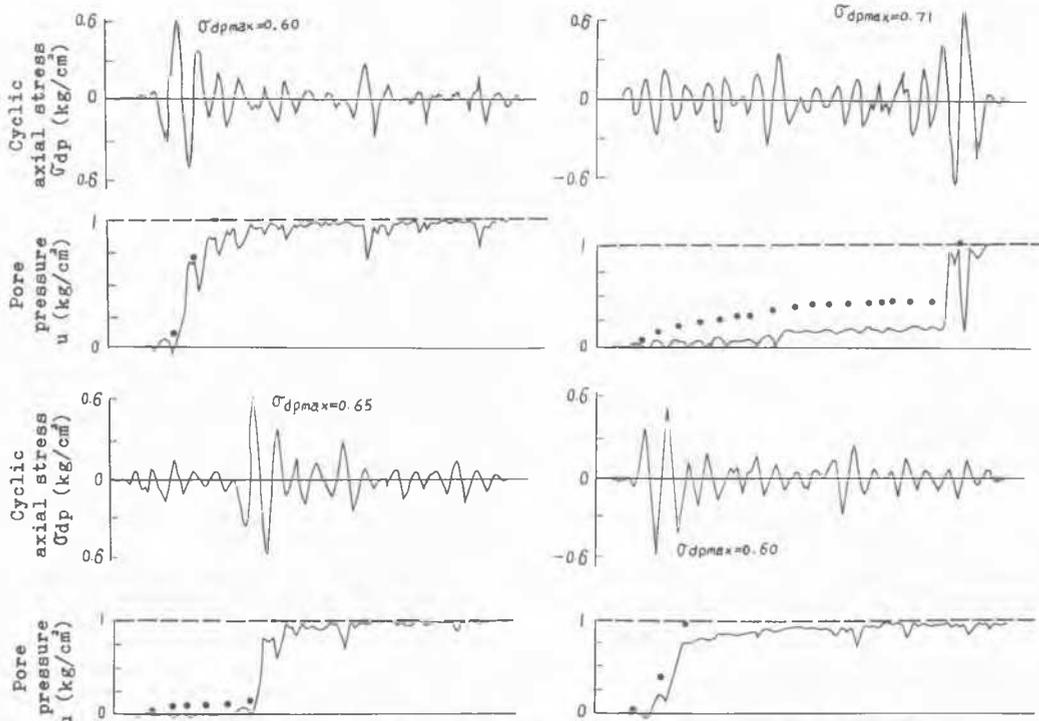


Fig.6 Verification of Model for Irregular Loading

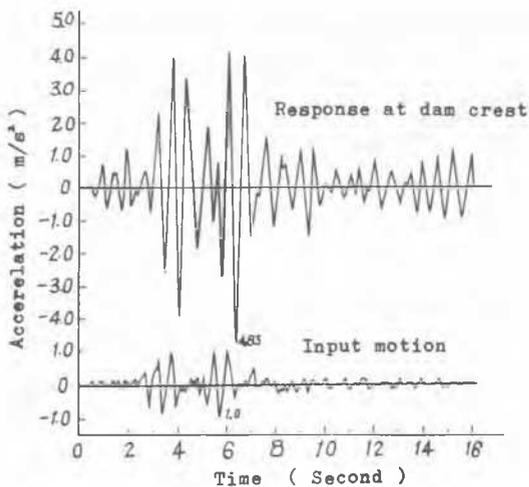


Fig.7 Input and Response Acceleration

VERIFICATION

The test data of random loading provided kindly by Shen C.K. (1978) are used to verify the validity of the proposed model. For Ottawa sand of $D_r = 65\%$ and $e = 0.61$, $k_s = 1050$ is computed from Eq.(13). Assuming $k = 6$ and $k_u = 840$, $c_1 = 0.0025$ is obtained from cyclic strength data when $c_2 = 3/4$ is used. c_3 and c_4 are not needed for the isotropically consolidated condition. The comparison between computed results and measured data is shown in Fig.6. It can be seen that the model gives some higher pore pressure values for low stress amplitude range.

APPLICATION

The previously developed computer program EFESD (Shen, 1980) is revised accordingly. Its capa-

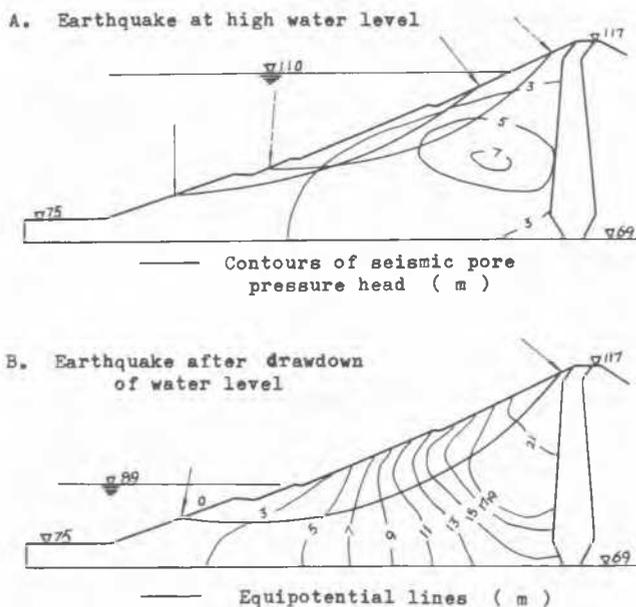


Fig.8 Seismic Pore Pressure and Potential Sliding Surfaces

bility of dealing with the seismic stability problems of earth structures is demonstrated by the following example.

Chaihe earth dam with sand shell and clay core is located in the north of Liaoning province. The stability of its upstream slope during an hypothetical earthquake is evaluated. The soil constants used in computation are: $k = 6$, $k_u = 1000$, $k_s = 780$, $c_1 = 0.0017$, $c_2 = 0.75$, $c_3 = 2.2$, $c_4 = 0.18$, $c_5 = 1$ and $\sin \phi = 0.7$. The input bedrock motion and response acceleration at the crest of dam are given in Fig.7. The computed pore pressure distribution and potential sliding surfaces with factor of safety equal to 1 at the end of earthquake for two particular cases of reservoir water level are shown in Fig.8. It is concluded from the analysis that the dam may suffer moderate but not catastrophic damage, probably like that which happened in the Shimenling earth dam located in the south of this province during Hai-cheng earthquake on Feb. 4, 1975 (Shen, 1981). The suggestion is that the reservoir should not be emptied in a hurry before a coming earthquake.

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